


Program at a Glance

September 18, Monday		
15:00-17:00 Registration (Entrance Lobby)		
September 19, Tuesday		
8:40-18:00 Registration (Entrance Lobby)		
Room A (Noh Theatre) 	Room B (Conf. Room 1)	Room C (Conf. Room 3)
9:20-9:50 Opening Session		
9:50-10:40 Keynote Session 1		
10:40-11:10 Exhibition Presentation		
11:10-11:40 Coffee Break		
11:40-13:00 TuA-A1 Obstacle Avoidance	11:40-13:00 TuB-A1 Point Cloud Data Processing	11:40-13:00 TuC-A1 Cooperation between Driver and Assistance System 1
13:00-14:00 Lunch (Reception Hall 1)		
14:00-15:40 TuA-P1 Risk Assessment	14:00-15:40 TuB-P1 Localization and Dynamic Map	14:00-15:40 TuC-P1 Driver Behavior Modeling 1
15:40-16:10 Coffee Break (Reception Hall 1)		
16:10-17:30 TuA-P2 Safety and Acceptance of Automated Driving	16:10-17:30 TuB-P2 Measurement and Sensing	16:10-17:30 TuC-P2 Driver Behavior Modeling 2
17:30-18:00 Photo Session (Entrance)		
18:00-20:00 Welcome Reception (Reception Hall 1)		
September 20, Wednesday		
8:30-17:00 Registration (Entrance Lobby)		
Room A (Noh Theatre) 	Room B (Conf. Room 1)	Room C (Conf. Room 3)
9:00-9:50 Keynote Session 2		
9:50-10:40 Keynote Session 3		
10:40-11:10 Coffee Break (Reception Hall 1)		
11:10-12:30 WeA-A1 Road Feature Image Processing		11:10-12:30 WeC-A1 Cooperation between Driver and Assistance System 2
12:30-13:30 Lunch (Reception Hall 1)		
13:30-15:10 WeA-P1 Path Planning 1	13:30-15:10 WeB-P1 Simulation Technology	13:30-15:10 WeC-P1 Driver Assistance System for Elderly Drivers
15:10-15:40 Coffee Break (Reception Hall 1)		
15:40-17:20 WeA-P2 Path Planning 2	15:40-17:20 WeB-P2 Safety Impact Assessment 1	15:40-17:20 WeC-P2 Driver Monitoring 1
18:30-20:30 FAST-zero'17 Party (Nara National Museum)		
September 21, Thursday		
8:30-13:00 Registration (Entrance Lobby)		
Room A (Noh Theatre) 	Room B (Conf. Room 1)	Room C (Conf. Room 3)
9:00-10:40 ThA-A1 Intersection Safety	9:00-10:40 ThB-A1 Safety Impact Assessment 2	9:00-10:40 ThC-A1 Driver Monitoring 2
10:40-11:10 Coffee Break (Reception Hall 1)		
11:10-12:30 ThA-A2 Driver Assessment 1	11:10-12:30 ThB-A2 Object and Space Detection	11:10-12:30 ThC-A2 Human Machine Interface 1
12:30-13:30 Lunch (Reception Hall 1)		
13:30-14:30 ThA-P1 Driver Assessment 2	13:30-14:30 ThB-P1 Vehicle Control	13:30-14:30 ThC-P1 Human Machine Interface 2
14:30-14:50 Coffee Break (Reception Hall 1)		
14:50-15:40 Keynote Session 4		
15:40-16:10 Closing Session & Best Paper Awards		

Timetable

September 19, Tuesday

	Room A (Noh Theatre) ㊟	Room B (Conf. Room 1)	Room C (Conf. Room 3)
9:20	Opening Session		
9:50	Keynote Session 1 Demand and mental resource control for driving safety Motoyuki Akamatsu		
10:40	Exhibition Presentation		
11:10			
	Room A (Noh Theatre) ㊟	Room B (Conf. Room 1)	Room C (Conf. Room 3)
	TuA-A1: Obstacle Avoidance Chair: Inagaki (Honda R&D Co., Ltd.)	TuB-A1: Point Cloud Data Processing Chair: Kato (The University of Tokyo)	TuC-A1: Cooperation between Driver and Assistance System 1 Chair: Suzuki (Kagawa University)
11:40	TuA-A1-1 Potentials of Friction Adaptive AEB Systems Henze, Jarisa	TuB-A1-1 Estimation of Lead Vehicle Kinematics Using Camera-Based Data for Driver Distraction Detection Feng, Bao, Jin, et al.	TuC-A1-1 Shared Authority Mode: Connecting Automated and Manual Driving for Smooth Authority Transfer Wada, Kondo
12:00	TuA-A1-2 Proposal of Advanced Emergency Braking System Adapted to the Road Surface Condition Tsukuda, Shiozawa, Mouri	TuB-A1-2 Prediction Method for Continuous Point Cloud Data Compression Using SLAM Information Tu, Takeuchi, Miyajima, et al.	TuC-A1-2 Investigation on Transient Haptic Shared Control Shirayama, Mouri
12:20	TuA-A1-3 Study on Deceleration Control for the Autonomous Frontal Obstacle Avoidance System using Evasive Steering Iwata, Hayashi	TuB-A1-3 3D Localization and Mapping Using Automotive Radar Degerman, Pernstal, Hammarsten, et al.	TuC-A1-3 Analysis of Driver-System-Interaction in Highly Automated Driving Sonka, Hafner, Wagner, et al.
12:40	TuA-A1-4 Robust Autonomous Emergency Braking for Cyclist Collision Avoidance Kim, Chae, Yi, et al.	TuB-A1-4 Local Stationary Map Based Object Boundary Tadjine, Blascheck, Philipp	TuC-A1-4 Driver Responses to Automated Driving System Limits Abe, Sato, Uchida, et al.
13:00			
	Room A (Noh Theatre) ㊟	Room B (Conf. Room 1)	Room C (Conf. Room 3)
	TuA-P1: Risk Assessment Chair: Shimizu (Toyota Central R&D Labs., Inc.)	TuB-P1: Localization and Dynamic Map Chair: Furukawa (Virginia Polytechnic Institute and State University)	TuC-P1: Driver Behavior Modeling 1 Chair: Kitazaki (National Institute of Advanced Industrial Science and Technology (AIST))
14:00	TuA-P1-1 Continuous Risk Measures for ADAS and AD Eggert, Puphal	TuB-P1-1 Evaluation of Map-Expansion Method Using Different Cameras for Autonomous Driving Maeda, Takahashi, Kojima	TuC-P1-1 Consideration about Driver's Eye Movement at The Intersection Turn Right Futagami, Thuboi, Mouri
14:20	TuA-P1-2 On the Effects of Anticipatory Modeling on Quality of Automated Steering of Simulated Car Nikulin, Podusenko, Tanev, et al.	TuB-P1-2 Vehicle Trajectory Estimation Based on HD maps Using Inexpensive Monocular Camera and GPS in Highway Akai, Takeuchi, Morales, et al.	TuC-P1-2 The Influence of Audio Warning Urgency and Situational Urgency on Collision Avoidance Performance Tunanunkul, Kaizuka, Zheng, et al.
14:40	TuA-P1-3 Human-Centered Risk Assessment for Improved Vehicle Safety using Front Vehicle Dynamic States through Vehicular Communication Shin, Yi	TuB-P1-3 Estimation of Ego-Vehicle's Position based on Image Registration Kazama, Kawakatsu, Akagi, et al.	TuC-P1-3 The Effects of Visual-Manual Distraction on Driver Behavior in Pedestrian Crash Situations Gaspar, Schwarz, Brown, et al.
15:00	TuA-P1-4 Safety Cushion: Context-Sensitive Hazard Anticipation - Objectified Driving Behavior of Experienced and Careful Drivers for Developing Context-Sensing Driving Assistance Systems - Raksincharoensak, Inoue	TuB-P1-4 Longitudinal Improvement for Self-Localization based on Mono-Camera and Traffic Signs Hashimoto, Yoneda, Yanase, et al.	TuC-P1-4 Evaluation of Deep Learning-Based Driving Signal Generation Methods for Vehicle Control Seiya, Hayashi, Takeuchi, et al.
15:20	TuA-P1-5 Threat Analysis and Risk Assessment of the EPS System for Highly Automated Driving Vehicle - Application of STAMP/STPA to Vehicle Cybersecurity - Yoneki	TuB-P1-5 Driving Situation Analysis with Relational Local Dynamic Maps (R-LDM) Graph-Based Environment Representation for ADAS and AD Eggert, Aguirre Salazar, Puphal, et al.	TuC-P1-5 Effect of Vehicle Control Algorithms on Eye Behavior in Highly Automated Vehicles Price, Lee, Dinparastdjadid, et al.
15:40			
	Room A (Noh Theatre) ㊟	Room B (Conf. Room 1)	Room C (Conf. Room 3)
	TuA-P2: Safety and Acceptance of Automated Driving Chair: Ishihara (JTEKT CORPORATION)	TuB-P2: Measurement and Sensing Chair: Ninomiya (Nagoya University)	TuC-P2: Driver Behavior Modeling 2 Chair: Abe (Japan Automobile Research Institute)
16:10	TuA-P2-1 Safety Analysis of Cooperative Adaptive Cruise Control in Vehicle Cut-in Situations Aramrattana, Englund, Jansson, et al.	TuB-P2-1 Method for Detecting Operation Mistakes with Accelerator Pedal Suzuki	TuC-P2-1 After the Fail: How Far will Drivers Drift after a Sudden Transition of Control Dinparastdjadid, Lee, Schwarz, et al.
16:30	TuA-P2-2 Model Predictive Control Approach to Design Practical Adaptive Cruise Control for Traffic Jam Takahama, Akasaka	TuB-P2-2 Study on Tire Condition Monitoring by Quasi Electrostatic Field Technology Kouno, Takiguchi, Suda	TuC-P2-2 Estimating Risk Levels Perceived by Individuals for Lane Change Scenes Bao, Miyajima, Takeuchi, et al.
16:50	TuA-P2-3 Study on Social Acceptance of Truck Platoon System Hashimoto, Sugimachi, Suda	TuB-P2-3 Cause and Effect Relationship between the Dynamics of Accelerator and Brake Pedals during Emergency Braking Podusenko, Nikulin, Tanev, et al.	TuC-P2-3 Estimation of Driver's Risk Feeling toward Driving Environment Using Neural Network Sheng, Li, Miyajima, et al.
17:10	TuA-P2-4 Understanding Non-Verbal Communication Between Vehicles and Pedestrians Toward Safer Automated Vehicles Toyoda, Fridman, Jenik, et al.	TuB-P2-4 Localization of Vehicle Inspection Sticker in a Single Image Zhang, Zhang, Akashi	TuC-P2-4 Investigation of Driving Behavior and Cognitive Ability Concerning Planning Process during Driving of Elderly Drivers Shino, Nakanishi, Imai, et al.
17:30			

17:30-18:00 Photo Session (Entrance)

18:00-20:00 Welcome Reception (Reception Hall 1)

September 20, Wednesday

	Room A (Noh Theatre) 🎭	Room B (Conf. Room 1)	Room C (Conf. Room 3)
9:00	Keynote Session 2 Road Condition Measurement and Suspension/ Traction Control for Active Safety and Autonomous Driving Tomonari Furukawa		
9:50	Keynote Session 3 Car Cures for FAST-zero Matthew Rizzo		
10:40			
	Room A (Noh Theatre) 🎭	Room B (Conf. Room 1)	Room C (Conf. Room 3)
	WeA-A1: Road Feature Image Processing Chair: Feng (University of Michigan Transportation Research Institute)		WeC-A1: Cooperation between Driver and Assistance System 2 Chair: Shino (The University of Tokyo)
11:10	<i>WeA-A1-1</i> Automatic Detection and Evaluation of 3D Pavement Defects Using 2D and 3D Information at the High Speed Hu, Furukawa		<i>WeC-A1-1</i> Drivers' Braking Behaviors in Different Motion Patterns of Vehicle-Bicycle Conflicts Hou, Duan, Wang, et al.
11:30	<i>WeA-A1-2</i> EPS Control Methodology for Straight Driving -Steering Power Assist in Straight Cant Road Iijima, Tamura		<i>WeC-A1-2</i> Study on Judgment of Override in Precision Docking by Shared Control Using Driving Simulator Sugimachi, Okada, Hayakawa, et al.
11:50	<i>WeA-A1-3</i> Selective Pre-Processing Method for Road Crack Detection with High-Speed Data Acquisition A First Step towards Intelligent Road Condition Monitoring Steckenrider, Furukawa		<i>WeC-A1-3</i> Optimal Design of Lane-keeping Assistance System Based on Driving Simulator and Vehicle Test Chen, Chen, Dang, et al.
12:10	<i>WeA-A1-4</i> Detection Technology of Road Marks Utilizing Combination of Partial Templates Nakamura, Ito, Kinoshita, et al.		<i>WeC-A1-4</i> The Confirmation the Safety Behavior of Expert Drivers and Elderly Drivers When Passing through Non Signalized Intersections Sato, Tsutsumi, Saito
12:30			
	Room A (Noh Theatre) 🎭	Room B (Conf. Room 1)	Room C (Conf. Room 3)
	WeA-P1: Path Planning 1 Chair: Yi (Seoul National University)	WeB-P1: Simulation Technology Chair: Suzuki (Nippon Institute of Technology)	WeC-P1: Driver Assistance System for Elderly Drivers Chair: Henze (Technische Universität Braunschweig)
13:30	<i>WeA-P1-1</i> Tube-based Path Generation Model of Merging onto Expressway in Dynamic Environment Mukouya, Yoshimoto, Fukao, et al.	<i>WeB-P1-1</i> Validating Test Cases for Safety Relevant ECUs using Simulation Models Alagöz, Schröder, Funda, et al.	<i>WeC-P1-1</i> Challenges and Solutions for ADAS 2020 and Beyond -On the Road towards Automated Driving- Adomat, Minami
13:50	<i>WeA-P1-2</i> Enhanced Path Planning in Urban Environment Using Knowledge Base Huy, Mita	<i>WeB-P1-2</i> Proving Ground Support for Automation of Testing of Active Safety Systems and Automated Vehicles Knauss, Berger, Eriksson, et al.	<i>WeC-P1-2</i> Analysis of Potential Risks to Sudden Appearance of Pedestrian While Passing a Parked Vehicle Focusing on Differences in Driving Skills Omoda, Iwaki, Abe, et al.
14:10	<i>WeA-P1-3</i> Comparative Evaluation of a Trajectory Generator for Obstacle Avoidance guaranteeing Computational Upper Cost Okawa, Nonaka	<i>WeB-P1-3</i> Holistically Simulation by Integration of Real Measurement Data Hafner, Krauns, Henze, et al.	<i>WeC-P1-3</i> Enhancing Risk Predictive Driving Performance of Elderly Drivers via Adaptive Shared Control Interface Saito, Shimono, Inoue, et al.
14:30	<i>WeA-P1-4</i> Improving Spatial Trajectory Planning by Using an Enhanced Road Representation Casapietra, Weisswange, Goerick, et al.	<i>WeB-P1-4</i> Benefits and Approach of Simulating a Million Hours for Automated Intelligent Transport Systems Method and Exemplary Application Seidel, Schwaiger, Krumbiegel, et al.	<i>WeC-P1-4</i> Study on Haptic Steering Shared Control between Driver and ADAS by Using Risk Potential Optimization Theory Inoue, Kinoshita, Mio, et al.
14:50	<i>WeA-P1-5</i> Trajectory Generation and Tracking Using Integrated Control of 4WS and DYC for Minimum Jerk Obstacle Avoidance Phuman Singh, Nishihara	<i>WeB-P1-5</i> Development of a Physics Based Radar Model (PBRM) in the PreScan Simulation Platform An End to End Radar Simulator for Automotive Environments Theo, van Putten, Liao, et al.	<i>WeC-P1-5</i> Reaction Tendencies of Elderly Drivers to Various Target Paths of Proactive Steering Intervention System in Human-Machine Shared Framework Ito, Takei, Kamata
15:10			
	Room A (Noh Theatre) 🎭	Room B (Conf. Room 1)	Room C (Conf. Room 3)
	WeA-P2: Path Planning 2 Chair: Tadjine (IAV GmbH)	WeB-P2: Safety Impact Assessment 1 Chair: Lich (Robert Bosch Corporation)	WeC-P2: Driver Monitoring 1 Chair: Wada (Ritsumeikan University)
15:40	<i>WeA-P2-1</i> Study on Course Generation Algorithm Using Risk Potential Driver Model Zhang, Kageyama	<i>WeB-P2-1</i> Safety Effect of Traffic Signal Prediction Systems Kinoshita, Imaizumi	<i>WeC-P2-1</i> Study of Driver Cognition on Expressways Using Driving Simulator and Measurement of Cortical Brain Activity Jeong, Sugimachi, Nakano, et al.
16:00	<i>WeA-P2-2</i> Control Target Calculation for an Autonomous Vehicle to Maintain Traffic Harmony in an Urban Area Kitazawa, Kaneko	<i>WeB-P2-2</i> An In-depth Field Study for the Investigation of Intersection Accidents Using the AIMATS- Methodology Landgraf, Erbsmehl, Yuasa	<i>WeC-P2-2</i> Feasibility Study for In-Vehicle Detection of Severe Cardiac Events Horan, Sorousmehr, Gunaratne, et al.
16:20	<i>WeA-P2-3</i> Safe and Ecological Speed Profile Planning Algorithm for Autonomous Vehicles Using a Parametric Multiobjective Optimization Procedure Orfila, Gruyer, Hamdi, et al.	<i>WeB-P2-3</i> Safety Impact Assessment of ADAS in Terms of Total Reliability as Human-Machine System Suzuki, Miichi, Asao	<i>WeC-P2-3</i> Criteria for Drowsy Driving Detection Based on Vehicle and Bio Signal Integration Oh, Park, Ryu, et al.
16:40	<i>WeA-P2-4</i> Sampling based Vehicle Motion Planning for Autonomous Valet Parking with Moving Obstacles Jeong, Kim, Jo, et al.	<i>WeB-P2-4</i> Addressing the Challenge of Validation of Active Safety Systems for Highly Automated Driving -Augmenting Real-World Driving Tests with Virtual Elements- Kallweit, Prescher, Gropengießer, et al.	<i>WeC-P2-4</i> Interaction between Thermal Comfort and Arousal Level of Drivers in Relation to the Changes in Indoor Temperature Gwak, Shino, Kamata
17:00	<i>WeA-P2-5</i> Development of Path-Generation Technology for Minimizing Fluctuation of Vehicle Dynamic Characteristics Kusumoto, Sugano, Yamamoto	<i>WeB-P2-5</i> DESH-G model and Preliminary Architecture for Multiple ADAS system Ito	<i>WeC-P2-5</i> Effects of Steering Control Function on Driver Behavior While Turning at an Intersection Saito, Uchida, Tsukuda, et al.
17:20			
18:30-20:30	FAST-zero'17 Party (Nara National Museum)		

September 21, Thursday

	Room A (Noh Theatre) 🎭	Room B (Conf. Room 1)	Room C (Conf. Room 3)
	ThA-A1: Intersection Safety Chair: Inoue (Kanagawa Institute of Technology)	ThB-A1: Safety Impact Assessment 2 Chair: Uchida (Japan Automobile Research Institute)	ThC-A1: Driver Monitoring 2 Chair: Miyajima (Nagoya University)
9:00	<i>ThA-A1-1</i> Support Vector Machine-based Target Intention Inference at Urban Intersection Kim, Jeong, Lee, et al.	<i>ThB-A1-1</i> Preliminary Effectiveness Estimates for Intersection Driver Assistance Systems in LTAP/OD Crashes Scanlon, Sherony, Gabler	<i>ThC-A1-1</i> Study on Driver's Status Monitoring System Aoki, Mouri, Akagi, et al.
9:20	<i>ThA-A1-2</i> Driver Assistance System to Prevent Unnecessary Deceleration at Signalized Intersection Using Signal Information Nakanishi, Yamazaki, Marumo, et al.	<i>ThB-A1-2</i> Characterization of Traffic Jam Accidents in Germany Puthan, Lubbe	<i>ThC-A1-2</i> A New Approach to Visual Attention Allocation Assessment for Automated Driving Research Lenneman, Toyoda, Domeyer
9:40	<i>ThA-A1-3</i> A Study on Steering Angle Control Method under Right/Left Cornering in an Intersection Kawakatsu, Kazama, Mouri	<i>ThB-A1-3</i> Impacts on a Test Setup for the Evaluation of Advanced Emergency Braking for Cyclists in Japan Using Event-Driver Recorder Data Lich, Sawaki	<i>ThC-A1-3</i> Driver Distraction Evaluation Using Reflex Eye Movement Simulation Le, Inagami, Hamada, et al.
10:00	<i>ThA-A1-4</i> Proactive Braking Control and Collision Avoidance Assistance System for Passing a Blind Spot in Intersection Fujinami, Raksincharoensak, Ulbricht, et al.	<i>ThB-A1-4</i> A Method for the Efficient Testing of New Automated Driving Functions Znamiec, Reuber, Henze, et al.	<i>ThC-A1-4</i> Anti-Reflecting Illuminating Technique for Robust Eye-Movement Tracking in Camera-Based Driver Drowsiness Monitoring Shi, Yang, Zhang, et al.
10:20	<i>ThA-A1-5</i> Modeling Vehicle Behavior with Neural Dynamics Durán, Englund, Habibovic, et al.	<i>ThB-A1-5</i> Potential Safety Benefit of ADAS Technologies In the US and Germany Bahouth, Murakhovsky, Zuhurudeen, et al.	<i>ThC-A1-5</i> Driver Monitoring Based on Facial Expression Images and Physiological Indices with Changes in Arousal Level Takahashi, Gwak, Shino, et al.
10:40			
	ThA-A2: Driver Assessment 1 Chair: Aoki (Nagoya University)	ThB-A2: Object and Space Detection Chair: Adomat (Continental Automotive Corporation)	ThC-A2: Human Machine Interface 1 Chair: Itoh (University of Tsukuba)
11:10	<i>ThA-A2-1</i> Driving Safety and Real-Time Glucose Monitoring in Insulin-Dependent Diabetes Merickel, High, Smith, et al.	<i>ThB-A2-1</i> Camera Based Detection of Pedestrians using Genetic Optimized Hough Forests Iwanczik, Türmer, Häsensch, et al.	<i>ThC-A2-1</i> Measurement of Visual Properties for Smart Lighting Kojima, Hiratsuka, Shiraki, et al.
11:30	<i>ThA-A2-2</i> Portable Alcohol Detection Device with Breath Recognition for Smart Keys - Evaluation of Sensor Unit for Portable Device - Wakana, Yamada, Sakairi	<i>ThB-A2-2</i> Foreground Grouping and Separation Algorithms for Object Detection with a Vehicle-mounted Fisheye Camera Ganbold, Zhang, Tomita, et al.	<i>ThC-A2-2</i> Development of a Safe Driving Guidance System that Targets 30 km/h Zones Strand, Suzuki, Peters
11:50	<i>ThA-A2-3</i> Advanced Driver-Assistance System to Encourage Motivation and Skill Improvement for Safe and Smooth Driving Hiraoka, Tachibana	<i>ThB-A2-3</i> Dense Motion Stereo for Parking Space Detection Akita, Yamamoto	<i>ThC-A2-3</i> Improving the Tactile Feeling of Brake Pedal by Means of Stochastic Resonance Tanev, Shimohara
12:10	<i>ThA-A2-4</i> Model-Based Methodology for Social Acceptance Assessment of Autonomous Driving Vehicle Furukawa	<i>ThB-A2-4</i> A Segmentation Based Approach for the Detection of Free Space with Fisheye-Cameras Tadjine, Evangelio	<i>ThC-A2-4</i> Objective Assessment of Vehicle Steering Feeling Based on Driver's Neuromuscular Characteristics Using Electromyogram Liu, Liu, Ji, et al.
12:30			
	ThA-P1: Driver Assessment 2 Chair: Hiraoka (Kyoto University)	ThB-P1: Vehicle Control Chair: Akita (AISIN SEIKI Co., Ltd.)	ThC-P1: Human Machine Interface 2 Chair: Strand (The Swedish National Road and Transport Research Institute (VTI))
13:30	<i>ThA-P1-1</i> Finite Element Analysis for Investigating the Effects of Muscle Activation on Head-neck Injury Risks of Drivers Rear-ended by a Car after an Autonomous Emergency Braking Iwamoto, Nakahira, Kato	<i>ThB-P1-1</i> A Lane Change Assist System Using V2V Communication and the Cooperation Test Wang, Kaizuka, Zheng, et al.	<i>ThC-P1-1</i> Design and Implementation of Vehicle Automatic Emergency Pull Over Strategy Using Active Safety Systems on a Driving Simulator Javaid, Deng, Chen, et al.
13:50	<i>ThA-P1-2</i> Towards an On-Demand Intersection Assistant -Initial User Acceptance and System Development- Heckmann, Wersing, Orth, et al.	<i>ThB-P1-2</i> Driver to Driver (D2D) Personalized Messaging Based on Connected Vehicles: Concept Evaluation via Simulation Rajab, Bai, Saigusa, et al.	<i>ThC-P1-2</i> Adaptive Vibration Suppression for Image of Head-Up Display Relative to the Background Hu, Kaizuka, Zheng, et al.
14:10	<i>ThA-P1-3</i> The Crash Avoidance Effect of a Lane Departure Warning System Isaksson-Hellman, Lindman	<i>ThB-P1-3</i> On the Implementation of Steering Controls for Evaluation of Automated Driving Systems in Driving Simulator Nguyen Van, Ito	<i>ThC-P1-3</i> A Methodology for Quantitative Assessment of Ghost Images on Head Up Display Ryu, Oh, Park
14:30			
14:50	Keynote Session 4 Making Mobility a great place to live Berthold Wolfram		
15:40	Closing Session & Best Paper Awards		
16:10			

September 22, Friday

Technical Visit